

# Comparative Study of Requirements for High Speed Crafts

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#### Factors forcing DNVGL to improve HSLC Rules

- Design of HSC primarily relying on Class Rules (High costs and time consumption to perform experiments and numerical simulations)
- Rapid development of HSC design and construction
- Introduction of new concepts and techniques
- Faster and larger HSCs being built
- Competition between different Classes

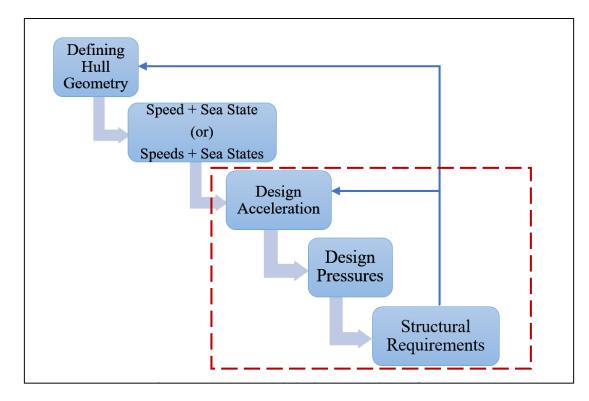
# Objectives

- To study the background of formulations in HSLC rules
- To verify the results presented in SSC Report (to compare DNV-HSLC and DNVGL-HSLC Rules)
- To identify application range of DNVGL-HSLC Rules
- To evaluate possibility of merger of DNVGL-HSLC and DNVGL-Naval Rules
- To identify shortcomings in the current DNVGL-HSLC rules

- Background study of HSLC rules
- Verification of SSC Report 439
- Comparison of DNVGL-HSLC and DNVGL-Naval Rules
- Conclusion and proposals

# Structural Design of High Speed Crafts

- Optimization of Strength (to resist loads) and Weight (for cost effectiveness and envionmental prospect)
- Involve several inter-steps and repititions
- Generally satisfy the procedures in figure.



### Background of DNVGL-HSLC rules

Design acceleration – based on Savitsky & Brown (1976)

Design pressures – based on Allen & Jones (1978)

Structural requirements – application of beam theory

### **Design Acceleration**

	U		
		Lower limit	Upper limit
<ul> <li>Savitsky &amp; Brown (1976)</li> </ul>	$\Delta_{\rm lt}/(0.01L_{\rm m})^3$	3531	8829
Avg acceleration (g's) in:	L/B	3	5
Avy acceleration (g s) III.	Deadrise, deg	10	30
$H_{1/2}$ $\tau$ 5 $\beta$ $V_{1}$ $L/b$	(β)	10	50
$\tilde{n}_{cg} = 0,0104 \left(\frac{H_{1/3}}{b} + 0.084\right) \frac{\tau}{4} \left(\frac{5}{3} - \frac{\beta}{30}\right) \left(\frac{V_k}{\sqrt{L}}\right)^2 \frac{L/b}{C_{\Delta}}$	Trim angle, deg	3	7
	(τ)	5	/
1/Nth highest acceleration:	H <sub>s</sub> /B	0.2	0.7
$\widetilde{n}_{\perp} \approx \widetilde{n}_{\perp} (1 + \ln N)$ $C_{\Delta} = \frac{\Delta}{h^3}$	V <sub>kn</sub> /sqrt(L <sub>m</sub> )	3.6	10.86
$\tilde{n}_{1/N} = \tilde{n}_{cg} (1 + \ln N)$			

#### • **DNVGL-HSLC** rules

Highest 1/100<sup>th</sup> average acceleration (5.6 times  $\tilde{n}_{cq}$ ) and Trim = 4 degree

$$a_{cg} = \frac{k_h g_0}{1650} \left( \frac{H_{si}}{B_{wl2}} + 0.084 \right) \left( 50 - \beta_{cg} \right) \left( \frac{V_i}{\sqrt{L}} \right)^2 \frac{L B_{wl2}^2}{\Delta}$$

**Range of Applicability** 

### **Design Pressures**

### • Allen & Jones (1978)

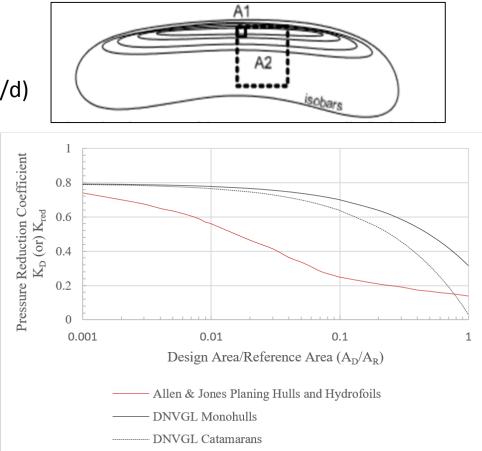
Key ideas

- formation of reference area ( $A_R = 0.7\Delta/d$ )
- momentary pressure distribution

$$P_D = \frac{\Delta N_Z}{0.14 A_R} K_D F$$

DNVGL-HSLC rules

$$p_{sl} = \frac{\Delta a_{cg}}{0.14 A_{ref}} K_{red} K_l K_\beta$$



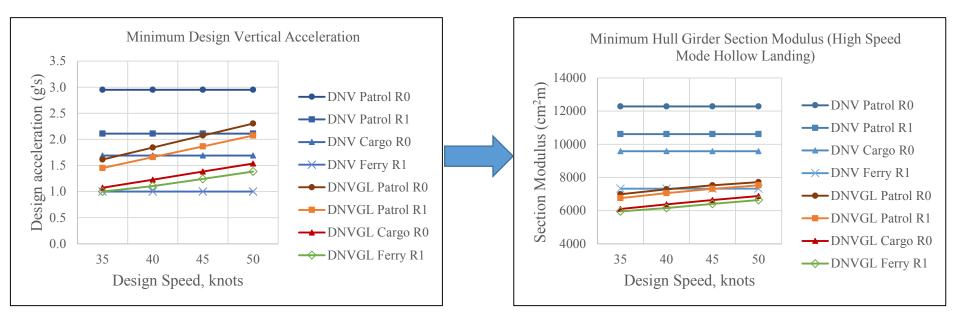
### Verification of SSC Report-439 (Comparison of DNV-HSLC and DNVGL-HSLC Rules)

- 61m Aluminium Monohull
- Speed range 35-50 knots (V/sqrt(L) between 4.5 and 6.4)
- Four different ship type & service notations Patrol R0, Patrol R1, Cargo R0, Ferry R1

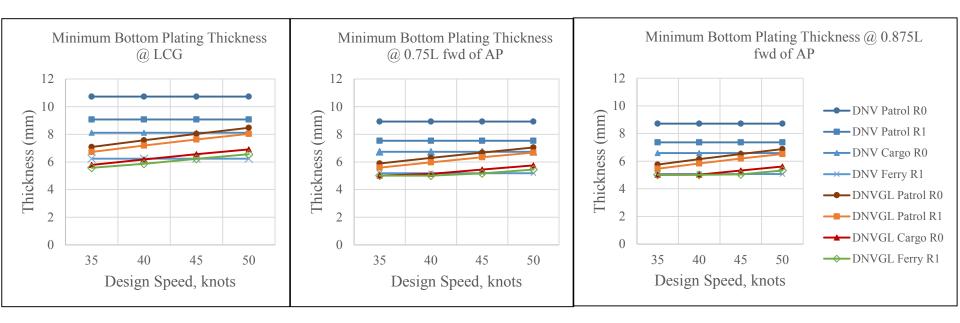
Description	Symbol	Unit	Value
Rule length	L	m	61
Moulded breadth	В	m	12.9
Draught	Т	m	2.7
Full load displacement	Δ	ton	950
Breadth at waterline	B <sub>WL</sub>	m	11.7
Position of LCG		m	25.7
Dead rise angle at LCG	β <sub>cg</sub>	degree	17

# Comparison of Veritcal Design Acceleration and Hull Girder Section Modulus

- Two kinds of hull bending moments
- Displacement Mode Cases (Still water + Sagging , Still water + Hogging) are F(ship parameters, wave coefficient)
- High Speed Mode Cases (Hollow landing , Crest landing) are F(ship parameters, vertical acceleration)



# **Comparison of Bottom Plating Thickness**

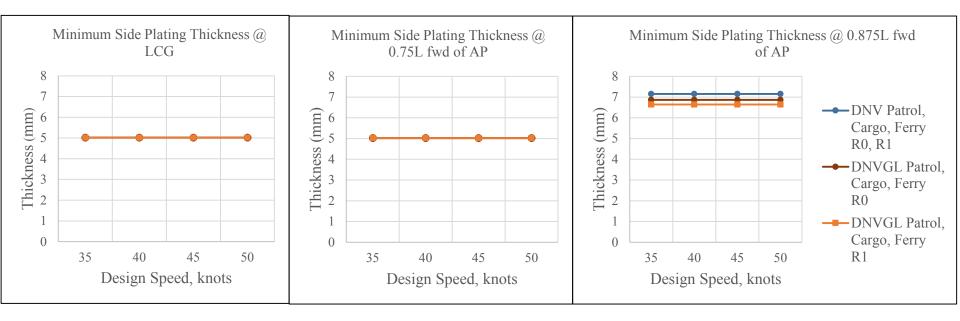


□ Heaviest scantlings near to LCG than forward parts due to

- vertical impact
- significant reduction in deadrise angle

Reduction of scantlings in DNVGL except for Ferry R1

# **Comparison of Side Plating Thickness**



**Heavier forward side elements subjecting to impact pressure** 

□ Aft side elements subjecting to sea pressure only

Similar scantlings between DNV and DNVGL

# Major Differences between DNV and DNVGL

DNV-HSLC	DNVGL -HSLC			
<ul> <li>Distance from port + wave height = service area</li> </ul>	• Distance from port defines service area.			
$a_{cg} = \frac{V}{\sqrt{L}} \frac{3.2}{L^{0.76}} f_g g_0$	$a_{cgi} = \frac{k_h g_0}{1650} \left(\frac{H_{si}}{B_{wl2}} + 0.084\right) (50 - \beta_{cg}) \left(\frac{V_i}{\sqrt{L}}\right)^2 \frac{L B_{wl2}^2}{\Delta}$ $a_{cgmin} = C_{HSLC} C_{RW} \frac{V_i}{\sqrt{L}}$			
• $\frac{V}{\sqrt{L}} \le 3$				
• $a_{cg}$ depends only on service area and ship type (f <sub>g</sub> )	<ul> <li>a<sub>cg</sub> depends on wave height and ship parameters.</li> </ul>			
<ul> <li>Constant design acceleration, pressures, and scantlings</li> </ul>	Acceleration increases as the speed increases.			
over a range of speeds where $\frac{V}{\sqrt{L}}$ > 3	<ul> <li>Speed reduction needs to be considered in case of high wave heights.</li> </ul>			
<ul> <li>too conservative for lower speeds and less for higher speeds</li> </ul>				
• Not fixing $\frac{V}{\sqrt{L}}$ may lead to more unrealistic values				

## Comparison of DNVGL-HSLC and DNVGL-Naval Rules

- Three high speed crafts with lengths between 30m to 80m
- 1<sup>st</sup> 37.5m Patrol Boat
  - Aluminium monohull
  - Deep-V, hard chine
- 2<sup>nd</sup> 61.9m Fast Attack Craft
  - Steel monohull
  - round-bilge
- 3<sup>rd</sup> − 79.9m Offshore Patrol Boat
  - Steel monohull
  - round-bilge

Description	Symbol	Unit	1 <sup>st</sup>	2 <sup>nd</sup>	3 <sup>rd</sup>
Length over all	LOA	m	37.5	61.9	79.9
Rule length	L	m	31.19	56.3	71
Moulded breadth	В	m	7.2	9.5	11.52
Moulded depth	D	m	5	6	7
Height above baseline	н	m	9.935	10.8	14.9
Draught	т	m	1.85	2.6	4.2
Full load displacement	Δ	ton	148.5	580	1670
Breadth at waterline	B <sub>WL</sub>	m	6.92	8.65	11.17
Dead rise angle at LCG	$\beta_{cg}$	degree	18	12	11
Significant wave height	H <sub>s</sub>	m	3	4.6	6.5

# Checking with Savitsky Limits

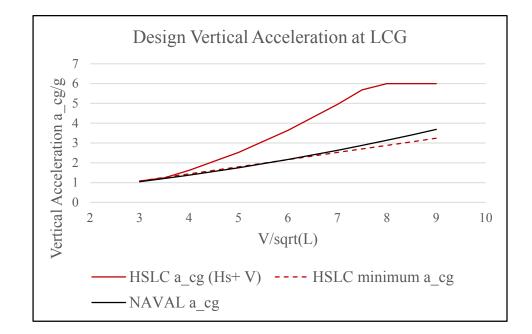
	Savitsky's Limit	37.5m	61.9m	79.9m
$\Delta_{it}/(0.01L_m)^3$	3531 – 8829	4894 (Yes)	3250 (No)	4665 (Yes)
L/B	3 – 5	4.5 (Yes)	6.5 (No)	6.4 (No)
Deadrise, deg (β)	10 - 30	18 (Yes)	12 (Yes)	11 (Yes)
Trim angle, deg (τ)	3 – 7	4 (Yes)	4 (Yes)	4 (Yes)
H <sub>s</sub> /B	0.2 – 0.7	0.4 (Yes)	0.5 (Yes)	0.6 (Yes)

□ Load calculations are done for a range of speeds (V/sqrt(L) between 3 and 9) to decide application limits.

□ Scantling calculations are done only for design speeds (29 knots, 34 knots, 30 knots).

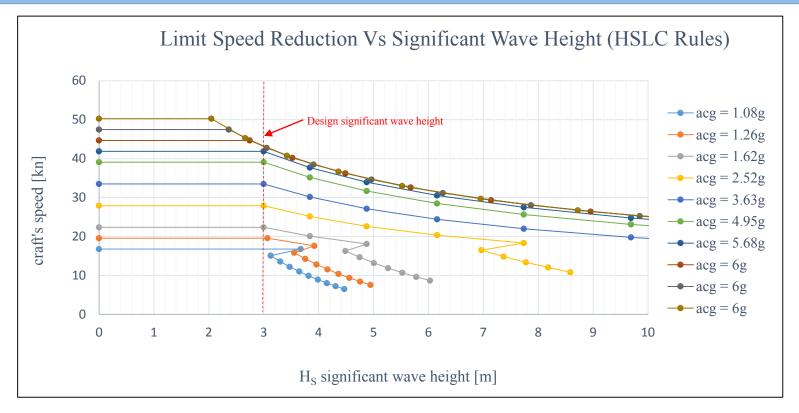
Comparison are done for all vessels. Results for only 37.5m patrol boat are shown below.

## **Comparison of Design Acceleration**



Minimum acceleration values from HSLC rules are used for comparison with Naval rules.
 Wave height-dependent accelerations are used to find the application range of HSLC rules.
 Maximum acceleration is reached when the speed is between 42 and 45 knots.

# Limit Speed Reduction in Higher Significant Wave Heights



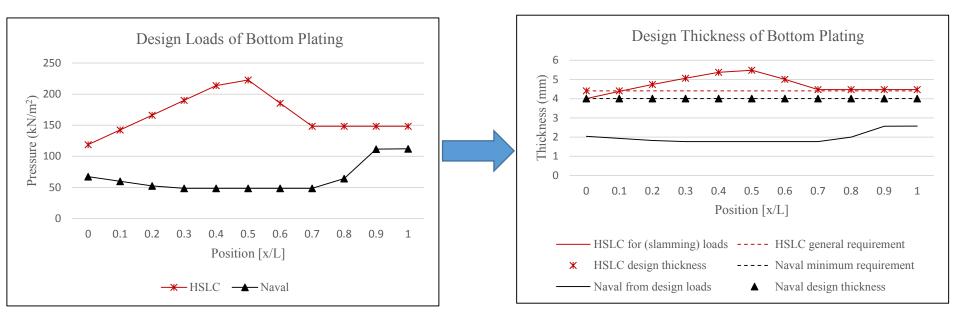
□ Maximum possible design speed ~ 42 knots at 6g (for design waveheight)

□ Formation of kinks around 17 knots (Switch of formulations at V/sqrt(L) = 3)

Reduction of design speeds

□ For acg=1.08g, 17 knots at 3m and 14 knots at 3.2m

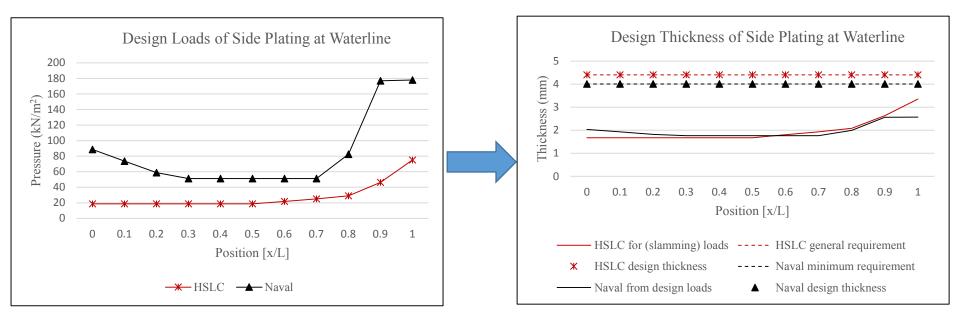
# **Comparison of Bottom Design Loads and** Scantlings



Different distribution and absolute values of load and scantlings  $p_{sl} = \frac{1}{0.14 A_{ref}}$  $\Box$  HSLC Rules – Reduction factor  $K_{red}$  increases as the element area decreases. □ Naval Rules –  $C_{A}$  (max) = 2  $p_{SL} = C_A c_{\alpha} c_{SL} (0.2 v_0 + 0.6 \sqrt{L})^2$ - constant load for all element areas < 5m<sup>2</sup>  $C_A = 1 + \frac{5}{4}$ - design element area of the ship =  $0.264m^2$ 

 $-K_{red}K_{l}K_{\beta}$ 

# Comparison of Side Design Loads and Scantlings



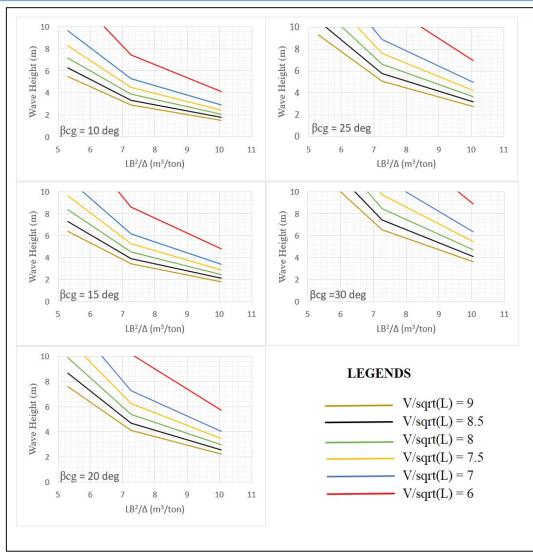
General thickness requirements in both rules are higher than thickness for design loads.

□ Same thickness required for different design loads.

Difference of permissible stresses – 225. 37 N/mm<sup>2</sup> in Naval rules

- 162 N/mm<sup>2</sup> in HSLC rules

# Limit Speeds for Applicability of DNVGL HSLC Rules



- □ Smoother lines are expected if more data are available Generally decides maximum speed that can be designed by DNVGL HSLC rules Based on maximum acceleration 6g, practical design accelerations differ □ 2g-3g for smaller crafts, 1g-1.5g for larger crafts (in Koelbel, 2000) Only for structural design (crew safety and comfort to be exclusively considered)
- □ Strictly valid for monohull HSCs

## Proposals for Improvements in DNVGL HSLC Rules

□ Allowance for higher trim angles

- Equilibrium trim angle = 4 degree
- 2 degree increase in trim cause 50% higher acceleration

Inclusion of Savitsky's Limits

- applicability is decided only by the speed currently
- V > 7.16 Δ<sup>0.1667</sup> knots

Revisions of Allen & Jones done by Razola et al. (2014)

- Comparison with experimental results, agreement observed only for panels with high aspect ratios near to the centerline
- addition of transverse distribution to contribute light weight
- correction factor for low aspect ratios (transversely framed hulls)

# Possibility of Merger?

□ Agreements in side design loads and scantlings

- each set of rules being well tuned
- adjust of permissible stress
- Disagreements in bottom design loads and scantlings
  - based on different background theories
  - different physics on load expectation
- DNVGL Naval Rules
  - Designated for longer vessels and larger stiffener spacings
  - Small bottom loads due to larger panel areas and less vertical motions
  - heavier scantlings close to waterline due to wave impact
- DNVGL HSLC Rules
  - more suitable for small crafts
  - shorter crafts subjected to more vertical motions
  - heavier bottom elements to resist high peak pressures from vertical impact \_

- X No Merger

# **Choice of Appropriate Rules**

Both DNVGL Naval Rules and DNVGL HSLC rules should be kept to cover a whole range of ships.

□Not easy to choose appropriate class rules only by ship type and speed

Should consider the followings:

- size of the ship
- expected behavior (high speed displacement mode or planning mode)
- Savitsky's Limits
- stiffening arrangement
- etc

# **Three Main Points of Master Thesis**

- Differences and improvements between DNV and DNVGL HSLC rules are studied.
- Applicability limits of DNVGL HSLC rules are developed for monohulls and
- possible improvements are proposed.
- Merger of HSLC rules and Naval rules is not recommended and it is important to choose the right design method to design specific ships.